

Task Model

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Major References:

Real-Time Computing, 國立交通大學, 張立平教授

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Terminologies (1/2)

- **Job**: a unit of work that is scheduled and executed by the system.
- **Task**: a set of related jobs which jointly provide some system function.
- The **release time** of a job: the instant of time at which the job becomes available for execution.
- **Response time**: the length of time from the release time of the job to the instant when it completes.

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Terminologies (2/2)

- The **deadline** of a job: the instant of time by which its execution is required to be completed.
 - **Relative deadline**: the maximum allowable response time of a job.
 - **Absolute deadline**: release time + relative deadline
- **Scheduler**: a scheduler is a module that allocates processors and resources to jobs and tasks.
- **Schedule**: an assignment of all the jobs in the system on the available processors produced by the scheduler.

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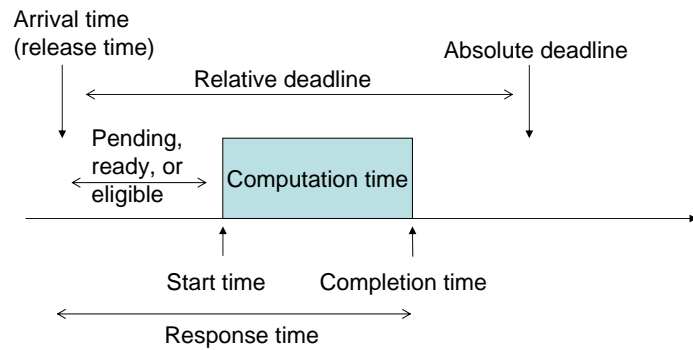
Feasible vs. Schedulable

- A valid schedule is a **feasible schedule** if every job completes by its deadline (or, in general, meets its timing constraints).
- A set of jobs is **schedulable** according to a scheduling algorithm if when using the algorithm the scheduler always produces a feasible schedule.

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System Model

- A job with real-time constraints

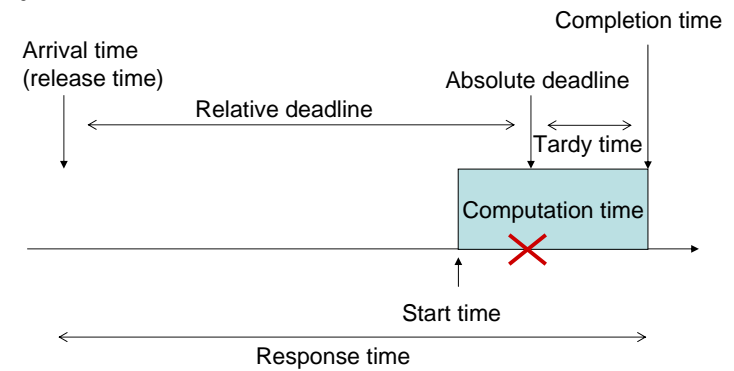


The job completes before its deadline, that means the deadline is satisfied.

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System Model

- A job with real-time constraints



The job completes after its deadline, that means the deadline is **violated** or an **overflow** occurs.

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Periodic Task Model (1/2)

- Each periodic task, denoted by T_i , is a sequence of jobs.
 - The **period** (p_i) of the periodic task T_i is the minimum length of all time intervals between release times of consecutive jobs in T_i .
 - The **execution time** (e_i) is the maximum execution time of all the jobs in it.
 - The release time $r_{i,1}$ of the first job $J_{i,1}$ in each task T_i is called the **phase** (ϕ_i) of T_i .
 - A job in T_i that is released at t must complete D_i units of time after t ; D_i is the **relative deadline** of the task T_i .

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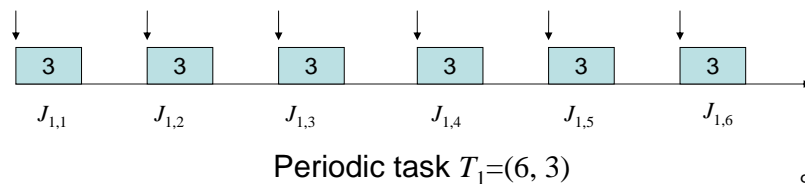
Periodic Task Model (2/2)

- **Priority**
 - Reflect the urgency of jobs
 - Any job inherits its task's priority
- **Preemptivity**
 - As a high-priority task arrives, it preempts the execution of any low-priority tasks

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A Purely Periodic Task

- Jobs of a task T recur every fixed time interval p
- A job must be completed before the next job arrives
 - Relative deadlines for jobs are, implicitly, the period
- T is defined as (p, c)



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Hard/Soft/Firm Real-Time Systems (1/2)

- Hard Real Time**
 - Hard real-time systems require a guarantee that *all* processing is completed within a given time constraint *every time*.
 - A late response may result in catastrophic consequences.
 - Examples of hard real-time systems include nuclear power plants and avionics control systems.
- Soft Real-Time**
 - Soft real-time systems have a less rigorous notion of temporal correctness and the consequences of a late response are not catastrophic.
 - Examples of soft real-time systems include telephone switches and electronic games.

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Hard/Soft/Firm Real-Time Systems (2/2)

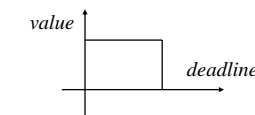
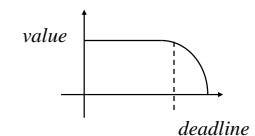
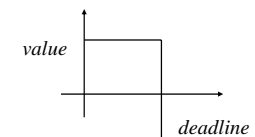
- Firm Real Time**
 - Firm real-time has been used to describe applications that require deterministic performance but not hard guarantees of performance.
 - Examples of firm real-time systems include video conferencing systems and network servers such as Web Service Providers (WSPs), Application Service Providers (ASPs), and those that support e-commerce.

<http://csce.unl.edu/~goddard/ResearchProjects/VariableRateResourceAllocation.html>

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Types of Real-Time Systems

- Hard real-time**
No deadline violation
- Soft real-time**
Low miss ratio or average/worst-case response time
- Firm real-time**
No value after deadlines expire



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